



Optimizing random searches under a time constraint using Lévy flights

Denis Boyer

Instituto de Física

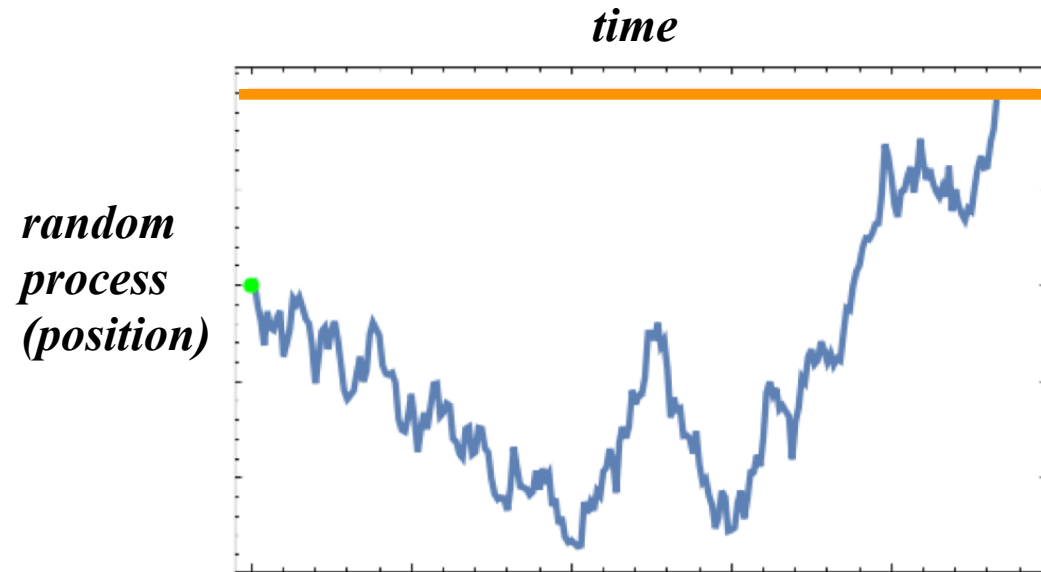
Universidad Nacional Autónoma de México, México City

Gabriel Mercado-Vásquez (IF-UNAM/University of Chicago)

Satya N. Majumdar (Paris-Saclay)

Grégory Schehr (Sorbonne Université)

First passage processes



Chemical reaction kinetics

Foraging animals

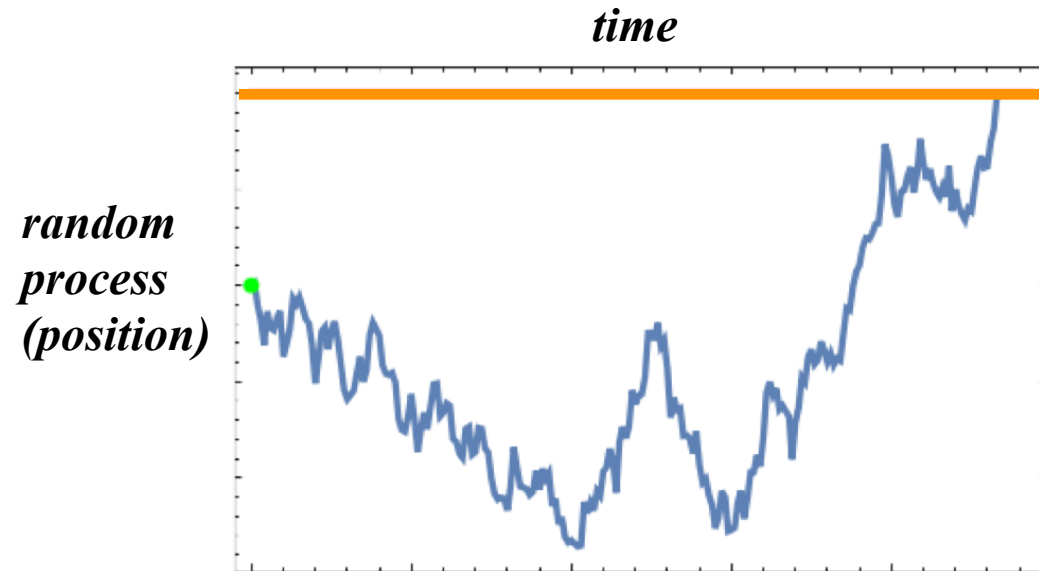
Seed dispersal

Finance

Rescue operations

....

First passage processes



Random movement of a “searcher”,
static target.

Chemical reaction kinetics

Foraging animals

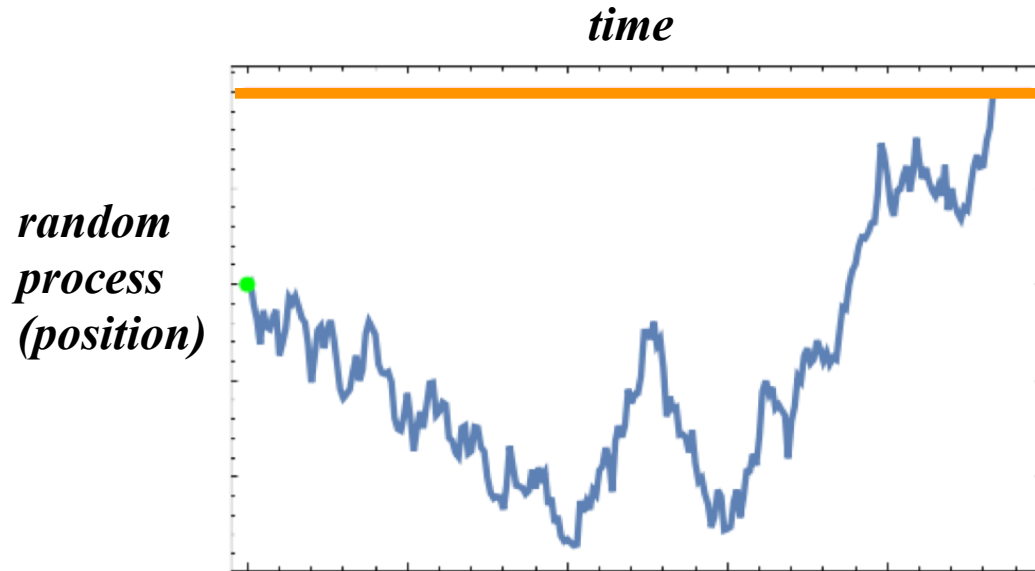
Seed dispersal

Finance

Rescue operations

....

First passage processes



Random movement of a “searcher”,
static target.

stochastic internal target dynamics

Chemical reaction kinetics

Foraging animals

Seed dispersal

Finance

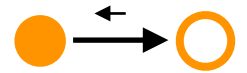
Rescue operations

....

reactive

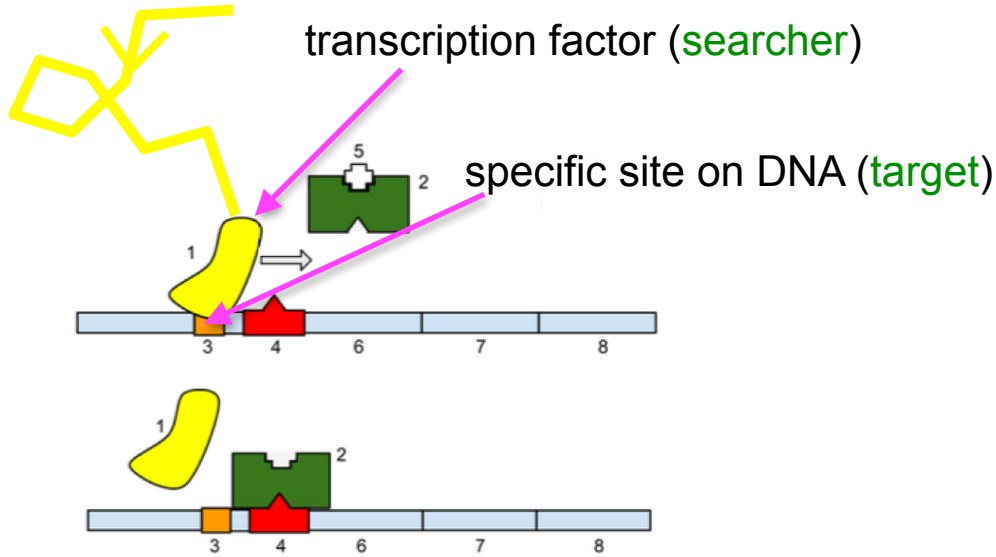


non-reactive



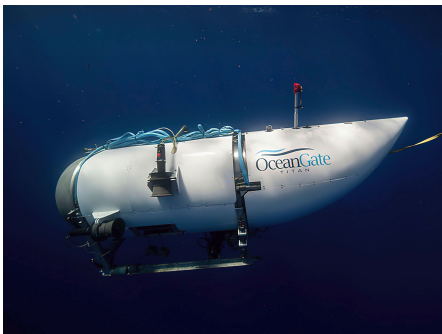
Random search processes with a time constraint

1) Gene regulation



(from Bénichou et al. RMP 2011)

2) Rescue



Sea operations
(Kosmas et al.,
Prod. Oper. Manag. 2022)

3) Animals with ephemeral resources



ripe fruit → rotten fruit

4) Give-up time

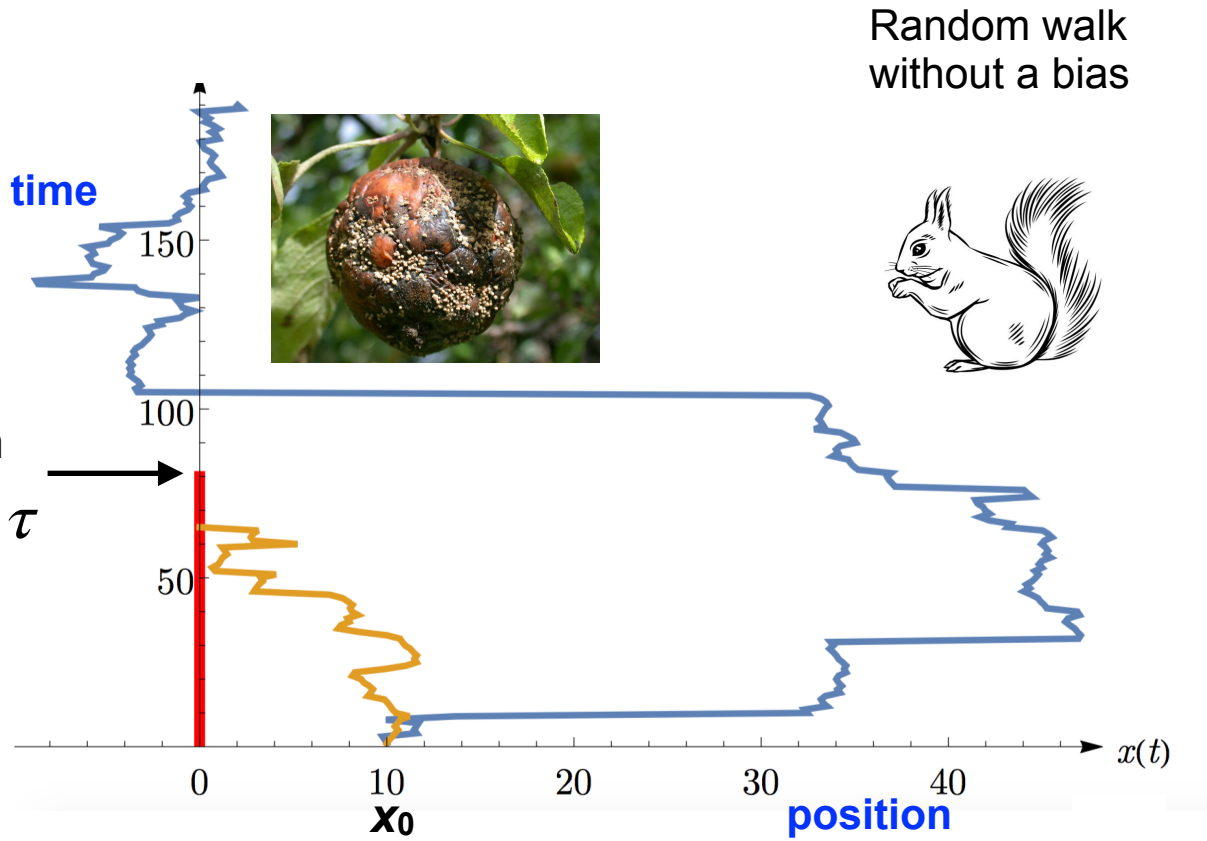
Search vehicle with limited autonomy
(Waharte et al. IEEE 2010)

Marginal value theorem
(Charnov, Theor. Pop. Biol., 1976)

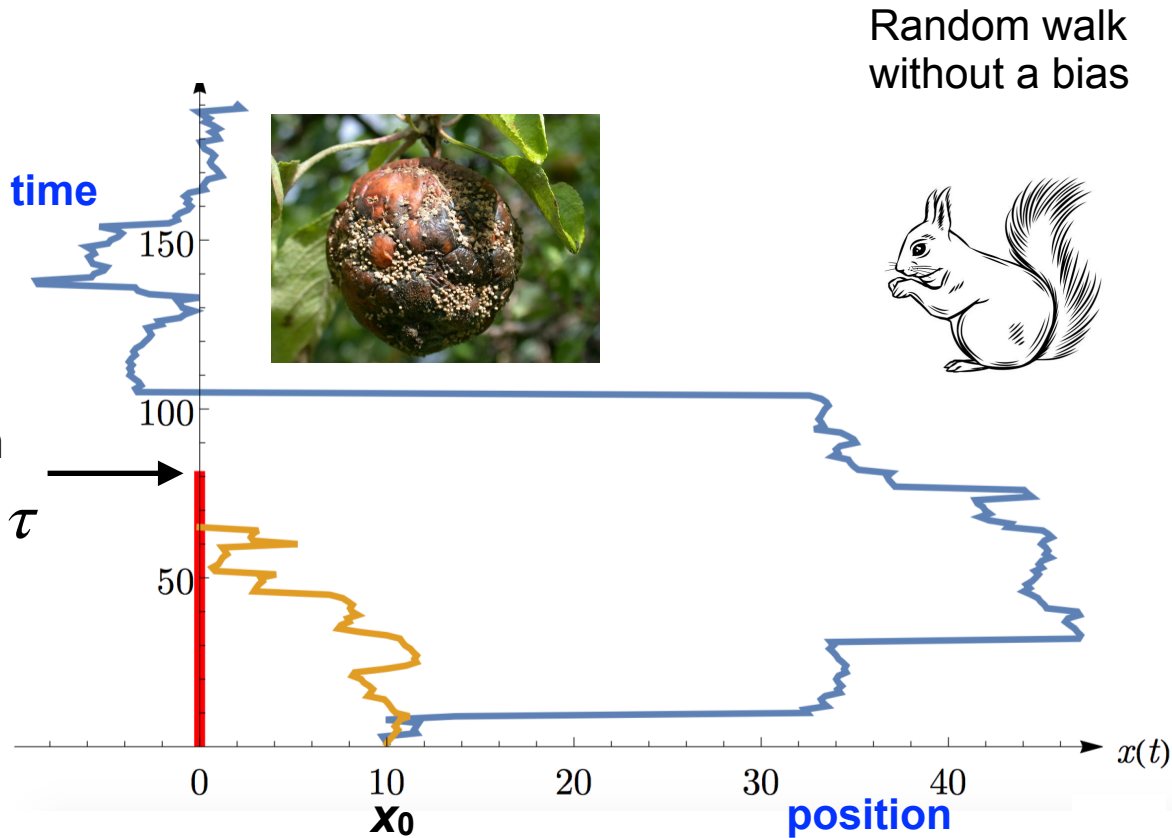
Mortal searcher (Yuste et al. PRL 2013)

Resetting processes
(Evans & Majumdar, PRL 2011)

Search of a finite-lived target



Search of a finite-lived target



Brownian limit (Meerson & Redner, PRL 2015):

$$\text{capture prob.} = e^{-\sqrt{\frac{\alpha}{D}}x_0} \quad \text{and} \quad \text{CMFPT} = \frac{x_0}{2\sqrt{D\alpha}} \quad \boxed{D \rightarrow \infty \text{ optimal}}$$

α : mortality rate

Outcome of a process failure/success improved by resetting (Belan, PRL 2018)

(if mortality rate is small enough)

Survival probability of a permanent target surrounded by a sea of mortal random walkers
(Yuste, Abad, Lindenberg, PRL 2013):

Mortal sub-diffusive searchers (Yuste, Abad, Yuste, Lindenberg, PRE 2012):

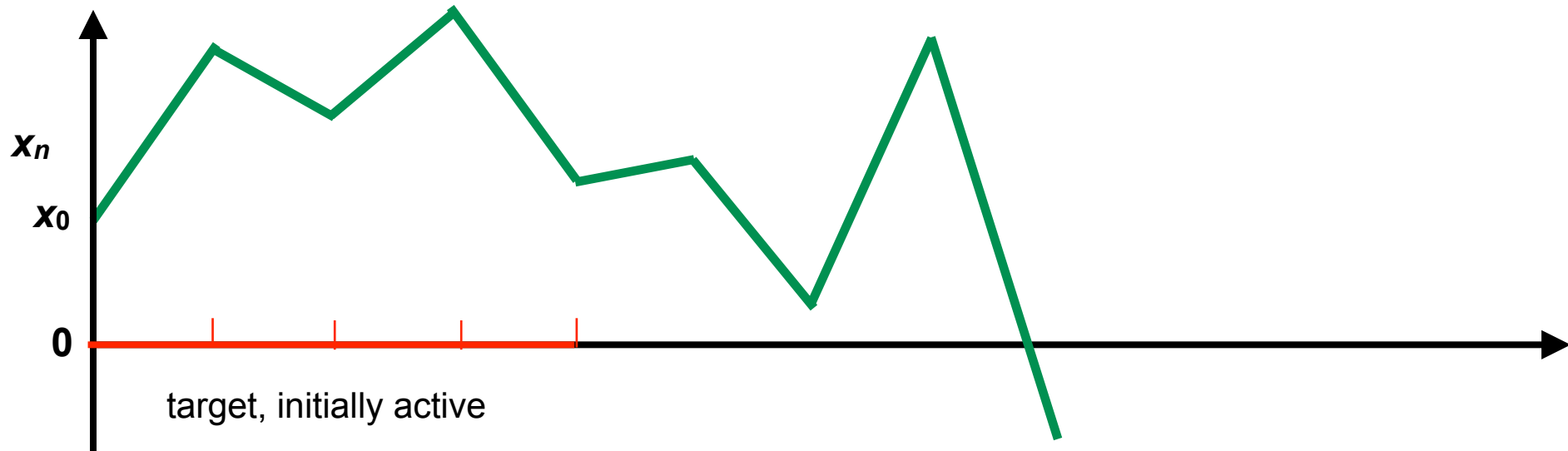
Formulation of a 1d model in discrete time:

$$x_0 > 0$$

$$x_n = x_{n-1} + \eta_n$$

η_n 's are i.i.d. variables distributed with $f(\eta)$

$f(\eta)$ is (i) continuous (ii) symmetric: $f(-\eta) = f(\eta)$



At each time step, the target stays alive with probability a ,
dies with probability $1 - a$.

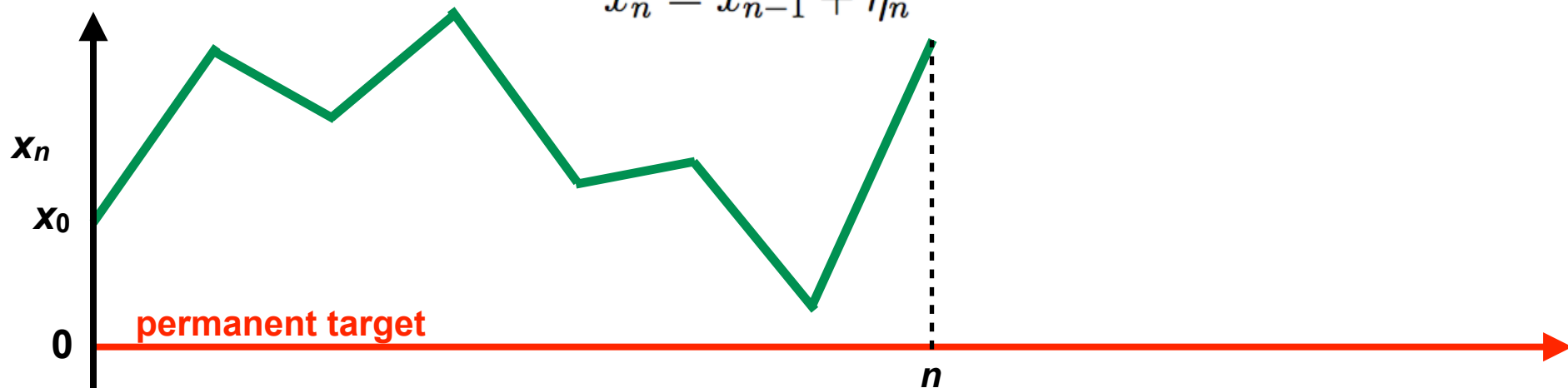
$$\langle t_{life} \rangle = 1/(1 - a)$$

(Markov processes for the searcher and the target)

A well known related problem ($a=1$):

$$x_0 > 0$$

$$x_n = x_{n-1} + \eta_n$$



$$Q_n(x_0) \equiv \text{Prob}[x_i \geq 0 \text{ for all } i = 1, \dots, n] \quad \text{"survival" probability}$$

$$\tilde{Q}(x_0, s) \equiv \sum_{n=0}^{\infty} s^n Q_n(x_0) \quad \text{generating function}$$

$$\int_0^{\infty} \tilde{Q}(x_0, s) e^{-\lambda x_0} dx_0 = \frac{1}{\lambda \sqrt{1-s}} \exp \left[-\frac{\lambda}{\pi} \int_0^{\infty} \frac{\ln[1 - s \hat{f}(k)]}{\lambda^2 + k^2} dk \right] \quad \text{Laplace transform}$$

Pollaczek-Spitzer formula (1952-1956)

Case $a=1$:

- The survival probability decays to 0 at large n :

$$Q_n(x_0) \simeq \frac{U(x_0)}{\sqrt{n}}$$

The capture probability is 1.

(Majumdar, Mounaix & Schehr, J. Phys. A, 2017)

- But the mean first passage time (MFPT) is infinite:

$$T(x_0) = \sum_{n=1}^{\infty} n [Q_{n-1}(x_0) - Q_n(x_0)] = \sum_{n=0}^{\infty} Q_n(x_0) = \infty$$

Basic quantities with a finite-lived target

Capture probability:

$$\begin{aligned} C_{x_0}(a) &= \sum_{n=1}^{\infty} a^{n-1} [Q_{n-1}(x_0) - Q_n(x_0)] \\ &= \frac{1 - (1-a)\tilde{Q}(x_0, s=a)}{a} \end{aligned}$$

maximum of $C_{x_0}(a) \iff$ minimum of $\tilde{Q}(x_0, s=a)$

Conditional mean first passage time (CMFPT):

$$\begin{aligned} T_{x_0}(a) &= \sum_{n=1}^{\infty} n a^{n-1} [Q_{n-1}(x_0) - Q_n(x_0)] / C_{x_0}(a) \\ &= a \frac{\partial}{\partial a} \ln [1 - (1-a)\tilde{Q}(x_0, s=a)] \end{aligned}$$

Basic quantities with a finite-lived target

Capture probability:

$$\begin{aligned} C_{x_0}(a) &= \sum_{n=1}^{\infty} a^{n-1} [Q_{n-1}(x_0) - Q_n(x_0)] \\ &= \frac{1 - (1-a)\tilde{Q}(x_0, s=a)}{a} \end{aligned}$$

maximum of $C_{x_0}(a) \iff$ minimum of $\tilde{Q}(x_0, s=a)$

Conditional mean first passage time (CMFPT):

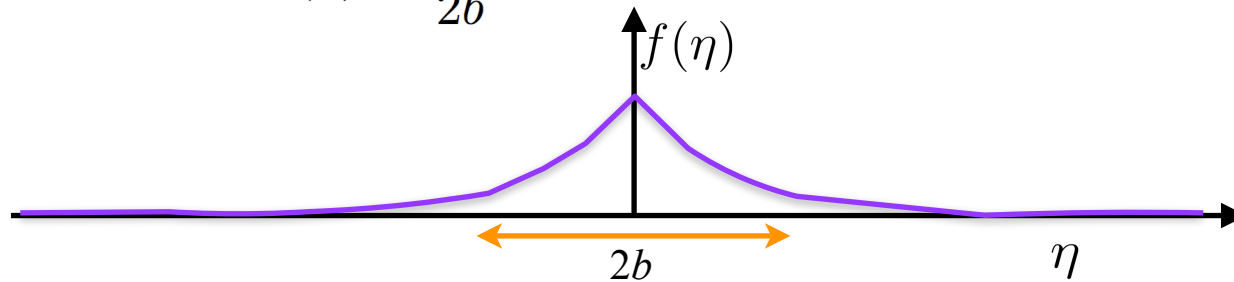
$$\begin{aligned} T_{x_0}(a) &= \sum_{n=1}^{\infty} n a^{n-1} [Q_{n-1}(x_0) - Q_n(x_0)] / C_{x_0}(a) \\ &= a \frac{\partial}{\partial a} \ln [1 - (1-a)\tilde{Q}(x_0, s=a)] \end{aligned}$$

 we don't have this directly

Exponential step distribution

(exactly solvable case)

$$f(\eta) = \frac{1}{2b} e^{-|\eta|/b}$$



Capture probability:

$$C_{x_0}(a) = \frac{1}{1 + \sqrt{1-a}} e^{-\frac{\sqrt{1-a}}{b} x_0}$$

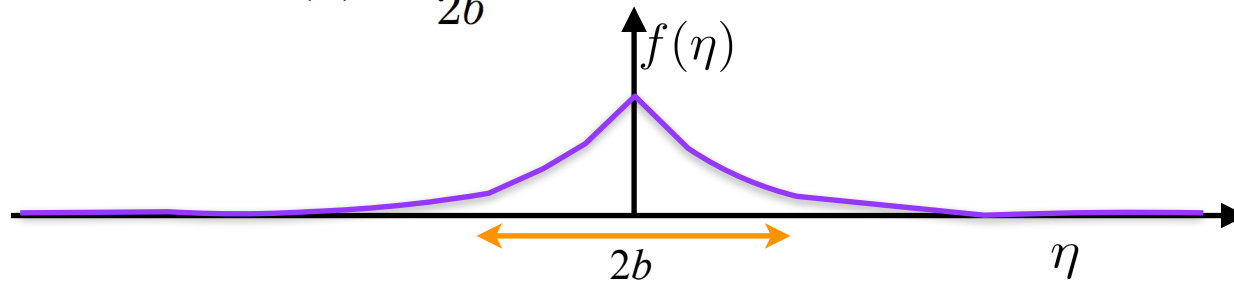
Conditional mean first passage time:

$$T_{x_0}(a) = \frac{1 + \sqrt{1-a}}{2\sqrt{1-a}} + \left(\frac{a}{2\sqrt{1-a}} \right) \frac{x_0}{b}$$

Exponential step distribution

(exactly solvable case)

$$f(\eta) = \frac{1}{2b} e^{-|\eta|/b}$$



Capture probability:

$$C_{x_0}(a) = \frac{1}{1 + \sqrt{1-a}} e^{-\frac{\sqrt{1-a}}{b} x_0}$$

Conditional mean first passage time:

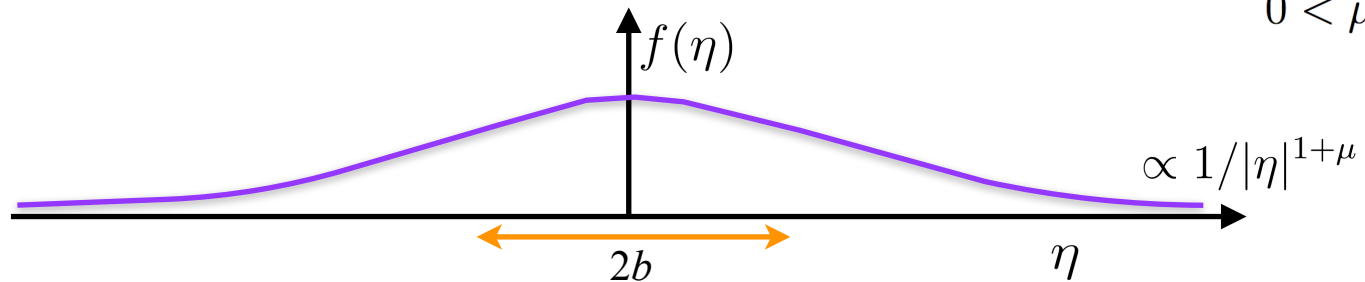
$$T_{x_0}(a) = \frac{1 + \sqrt{1-a}}{2\sqrt{1-a}} + \left(\frac{a}{2\sqrt{1-a}} \right) \frac{x_0}{b}$$

Optimal parameter: $b = \infty$

Lévy step distribution

Let us consider a Lévy distribution for the RW steps: $\hat{f}(k) = e^{-|bk|^\mu}$

$$b = 1 \\ 0 < \mu < 2$$



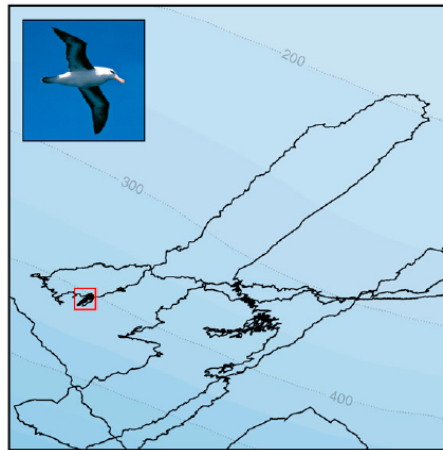
Value of μ that maximises the capture probability, or minimizes $\tilde{Q}(x_0, s = a)$: $\mu_{cap}^*(x_0, a)$

Value of μ that minimises the CMFPT: $\mu_{FP}^*(x_0, a)$

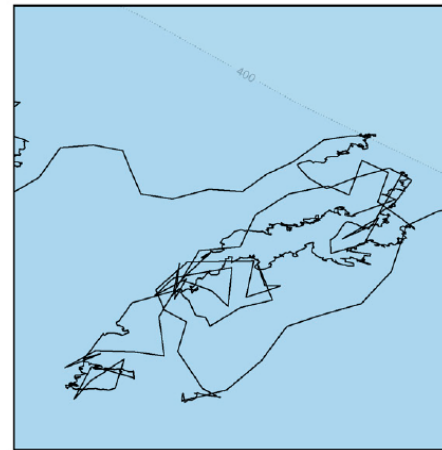
$$(\mu_{FP}^* \neq \mu_{cap}^*)$$

Lévy processes in biology

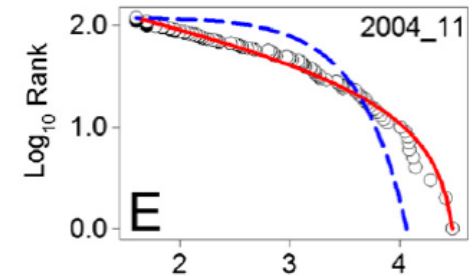
Albatross



0 5 10 Km

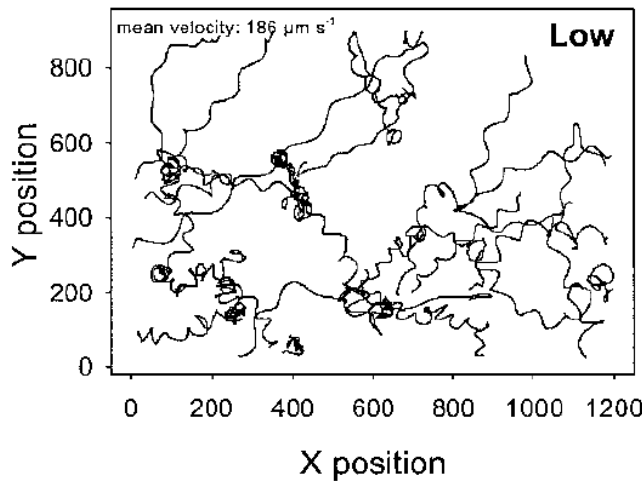


0 0.2 0.4 Km

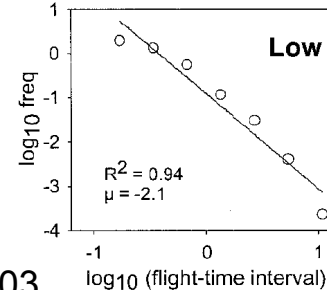
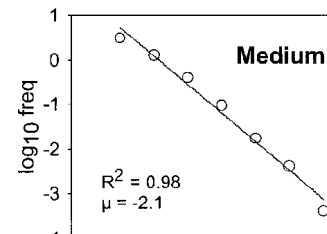


Humphries *et al.* PNAS, 2012

Microzooplankton



Bartumeus *et al.*, PNAS 2003

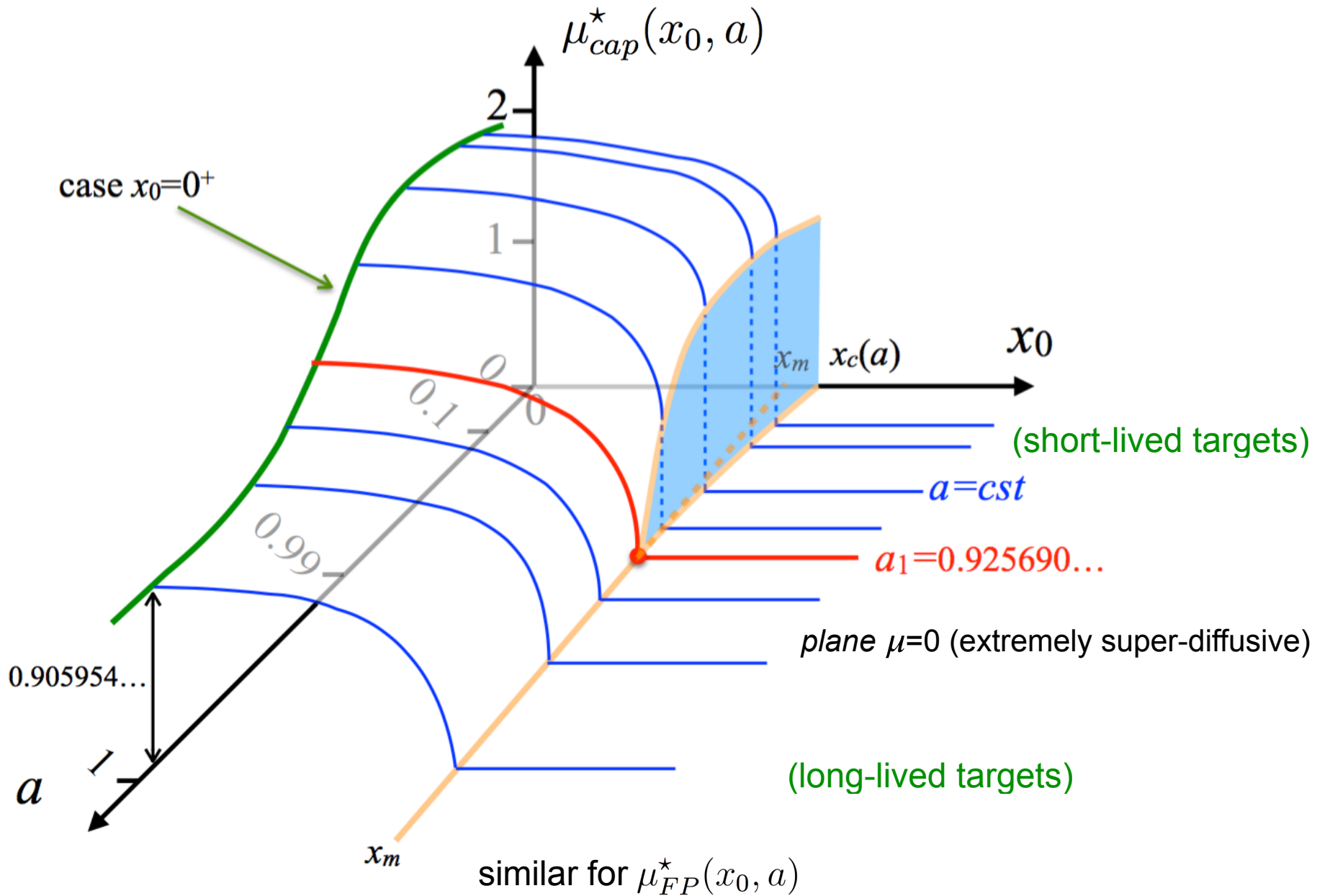


$$\mu \sim 1$$

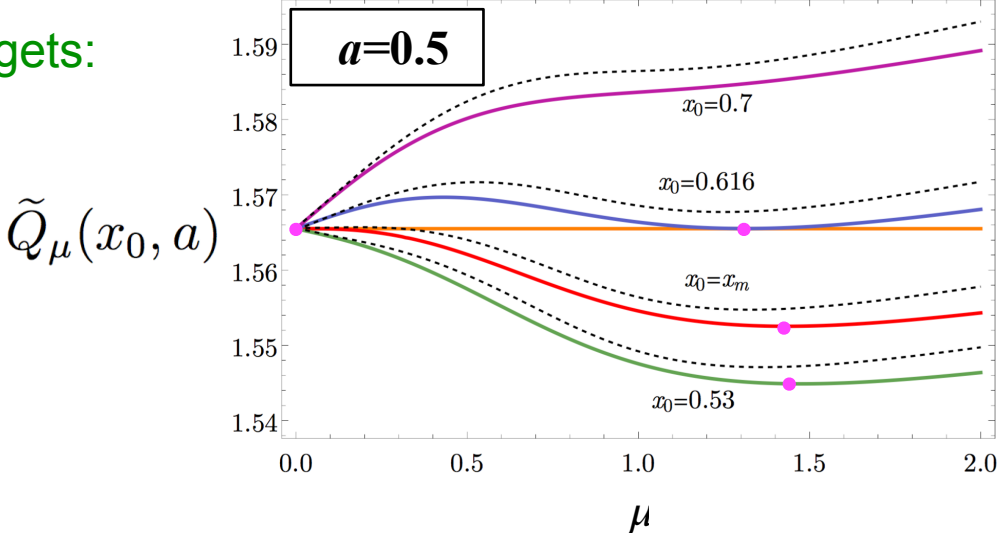
(optimal parameter in LFH, Viswanathan *et al.* Nature 1999.)

And: fruit flies,
mussels,
fishermen,
nomadic tribes,
bank notes,
cell phone users,
spider monkeys,
bumblebees, T-cells...

Main results (numerical & analytical)

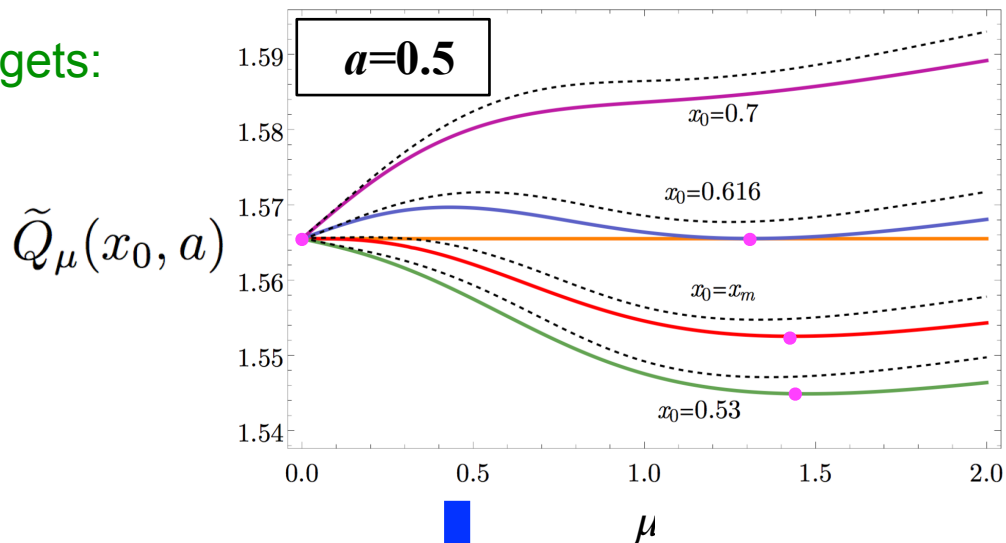


Short-lived targets:



$$x_m = e^{-\gamma E} = 0.56145\dots$$

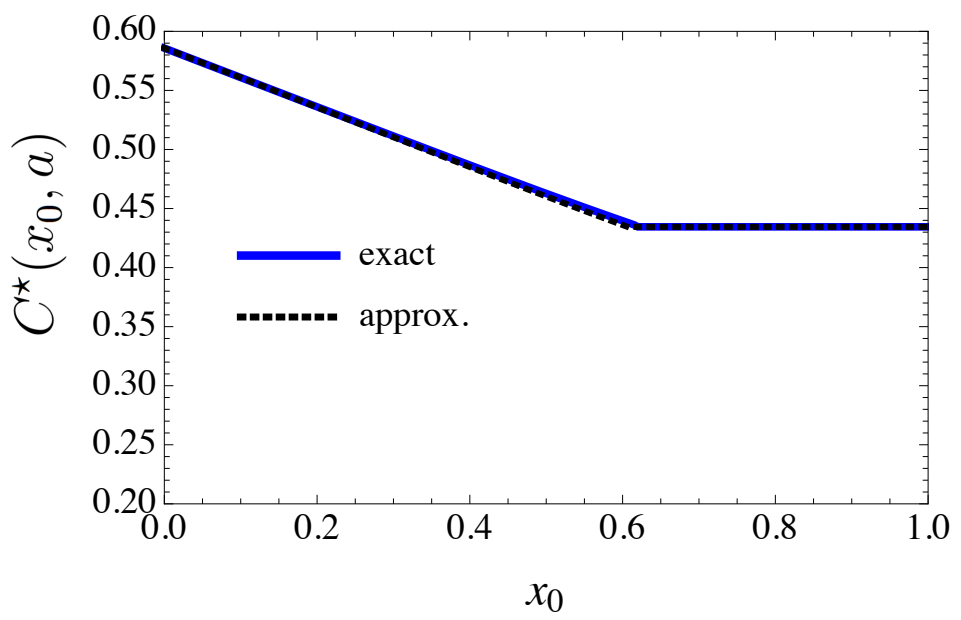
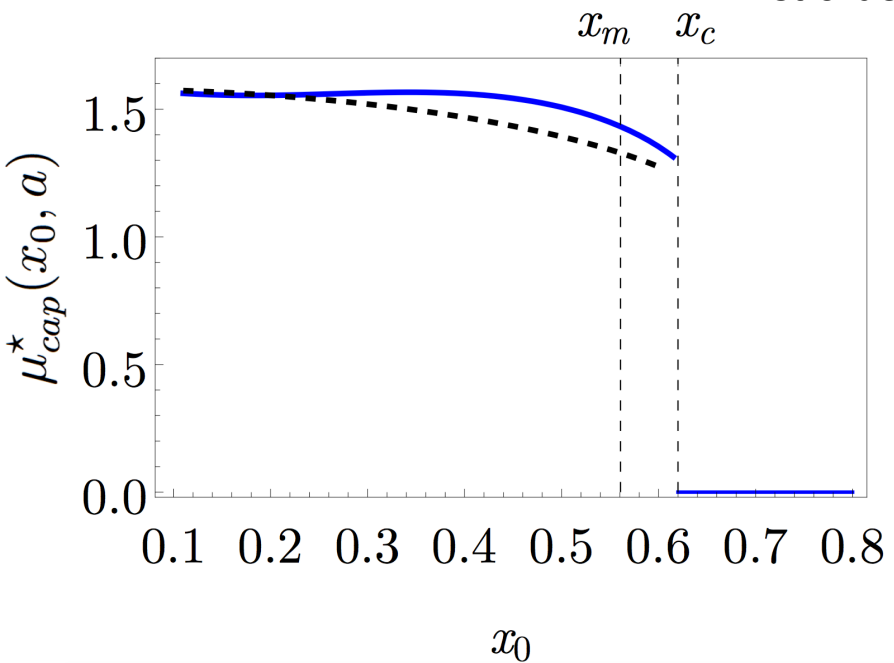
Short-lived targets:



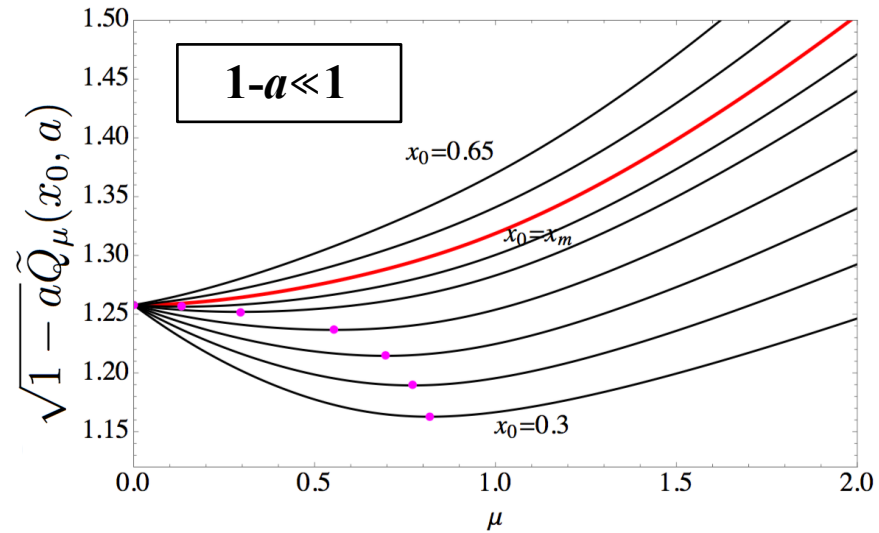
$$x_m = e^{-\gamma E} = 0.56145\dots$$



First order "phase" transition



Target with a sufficiently long lifetime:



Second order “phase” transition

Series expansion

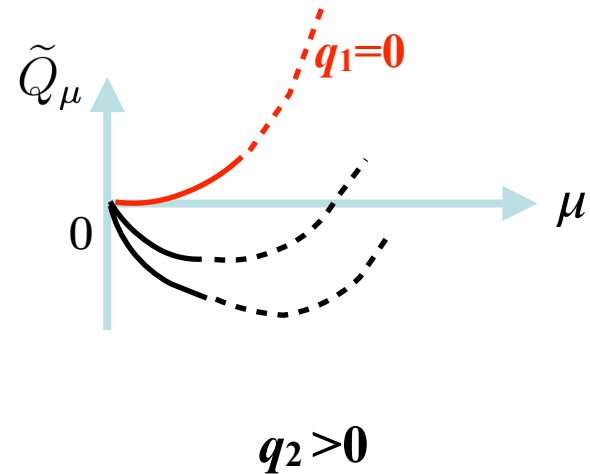
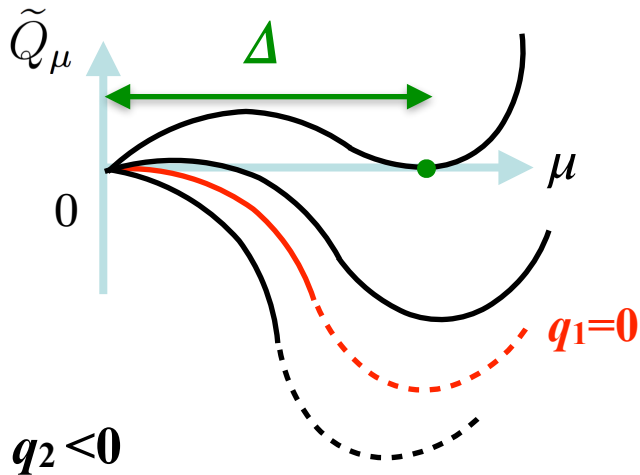
at small μ :

$$\tilde{Q}_\mu(x_0, a) = q_0 + q_1\mu + \frac{1}{2!}q_2\mu^2 + \frac{1}{3!}q_3\mu^3 + \dots$$

μ : positive "order" parameter

x_0 : "control" parameter

q_1 changes sign.



Simple scenario of first order transition: $q_2 < 0$, $q_3 > 0$.

$$\Delta = - \left. \frac{3q_2}{2q_3} \right|_{x_c}$$

Tri-critical point: $q_2 = 0$ (and $q_1 = 0$)

Non-conventional scenario of first order transition: $q_2 \geq 0$, $q_3 < 0$, ($q_4 > 0$)

$$\tilde{Q}(x_0, a) = q_0 + q_1\mu + \frac{1}{2!}q_2\mu^2 + \frac{1}{3!}q_3\mu^3 + \frac{1}{4!}q_4\mu^4 + \dots$$

$$\Delta = \frac{2}{3q_4} \left(2|q_3| + \sqrt{4q_3^2 - 9q_2q_4} \right) \Big|_{x_c}$$

Tri-critical point: $q_2 = 0$, $q_3 = 0$ (and $q_1 = 0$)

Non-conventional scenario of first order transition: $q_2 \geq 0$, $q_3 < 0$, ($q_4 > 0$)

$$\tilde{Q}(x_0, a) = q_0 + q_1\mu + \frac{1}{2!}q_2\mu^2 + \frac{1}{3!}q_3\mu^3 + \frac{1}{4!}q_4\mu^4 + \dots$$

$$\Delta = \frac{2}{3q_4} \left(2|q_3| + \sqrt{4q_3^2 - 9q_2q_4} \right) \Big|_{x_c}$$

Tri-critical point: $q_2 = 0$, $q_3 = 0$ (and $q_1 = 0$)

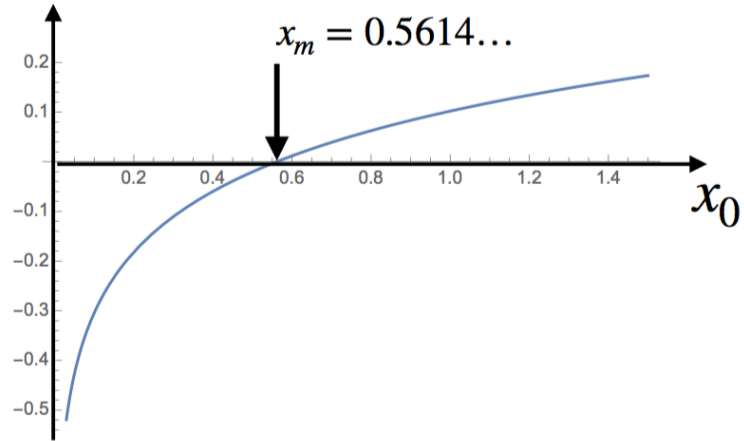
In our problem it turns out that q_1 and q_2 always vanish at the same time (at $x_0 = x_m$)

$$q_1 = \frac{ae^{-1}}{2\sqrt{1-a}(1-ae^{-1})^{3/2}} (\ln x_0 + \gamma_E) \quad \Rightarrow \quad q_1 = 0 \text{ at } x_m = e^{-\gamma_E} \quad \forall a$$

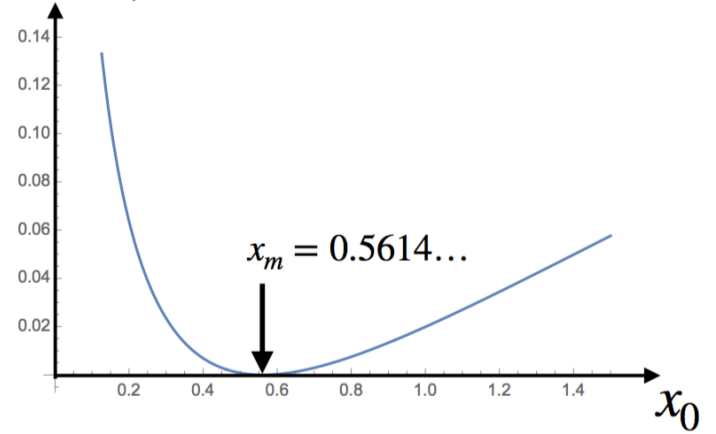
PS \Rightarrow

$$q_2 = \frac{3\sqrt{ea^2}}{4\sqrt{1-a}(e-a)^{5/2}} (\ln x_0 + \gamma_E)^2 \quad \Rightarrow \quad q_2 = 0 \text{ at } x_m = e^{-\gamma_E} \quad \forall a$$

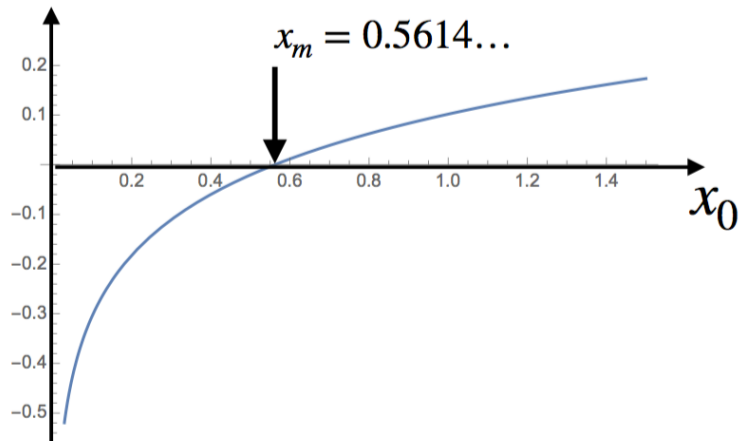
$$q_1(x_0, a = 1/2)$$



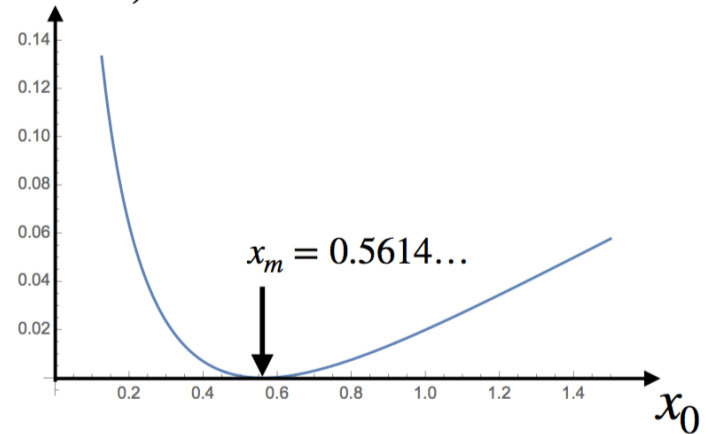
$$q_2(x_0, a = 1/2)$$



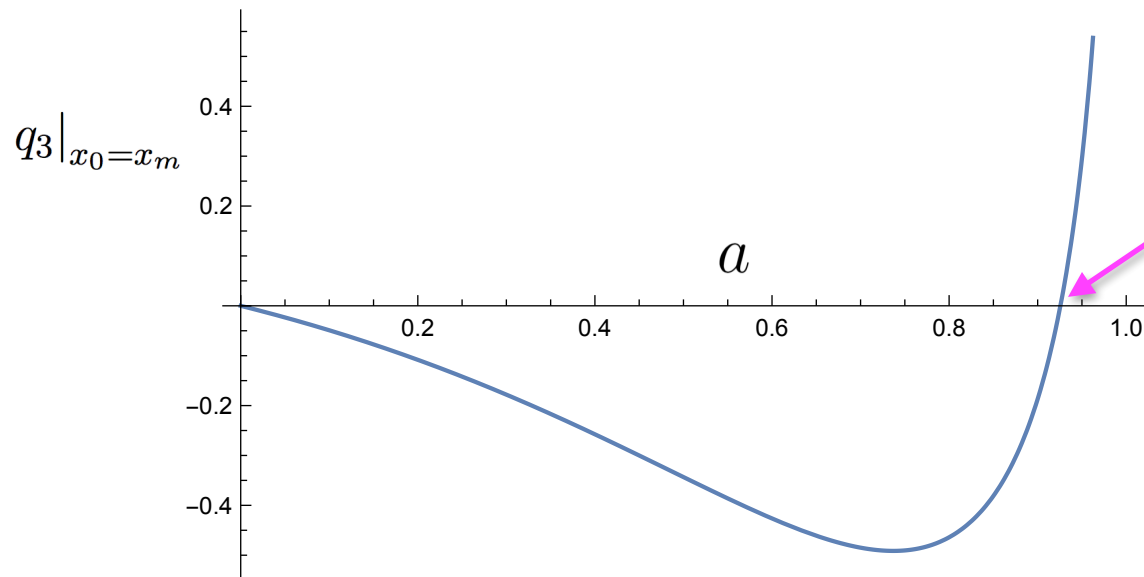
$$q_1(x_0, a = 1/2)$$



$$q_2(x_0, a = 1/2)$$



$$q_3|_{x_0=x_m} = \frac{a\sqrt{e}K}{8\sqrt{1-a}(e-a)^{7/2}}(11a^2 + 8ea - 4e^2) \quad \text{with } K = 2\zeta(3) = 2.4041138\dots$$



changes sign at

$$a_1 = \frac{2e(\sqrt{15} - 2)}{11} = 0.925690\dots$$

Conditional mean first passage time

series expansion
at small μ :

$$T_\mu(x_0, a) = t_0 + t_1\mu + \frac{1}{2!}t_2\mu^2 + \frac{1}{3!}t_3\mu^3 + \dots$$

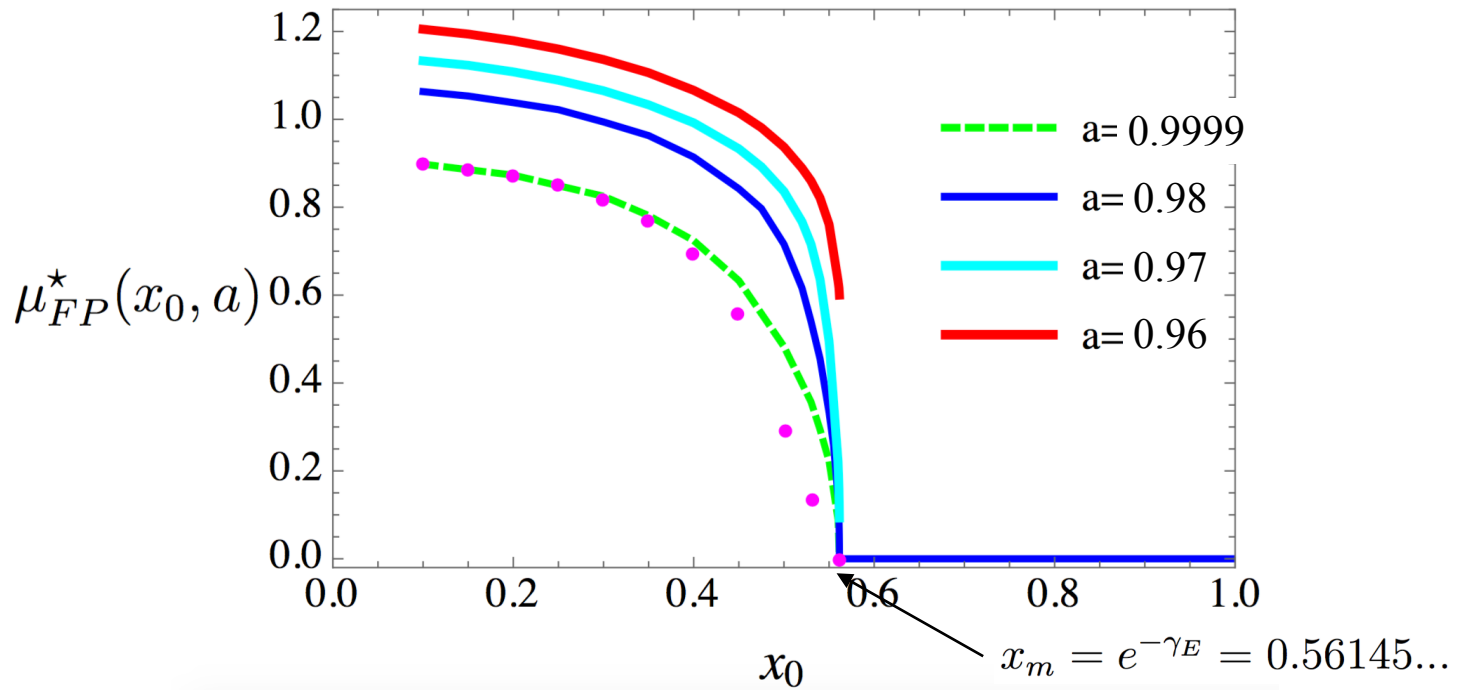
$t_3|_{x_0=x_m}(a)$ changes sign at $a_2 = 0.973989\dots$

Conditional mean first passage time

series expansion
at small μ :

$$T_\mu(x_0, a) = t_0 + t_1\mu + \frac{1}{2!}t_2\mu^2 + \frac{1}{3!}t_3\mu^3 + \dots$$

$t_3|_{x_0=x_m}(a)$ changes sign at $a_2 = 0.973989\dots$



Approximate inversion of Pollaczek-Spitzer

Concavity of the logarithm:

$$\lambda \int_0^\infty \ln[\tilde{Q}_\mu(x_0, s)] e^{-\lambda x_0} dx_0 \leq \ln \left[\lambda \int_0^\infty \tilde{Q}_\mu(x_0, s) e^{-\lambda x_0} dx_0 \right]$$



$$\Rightarrow \tilde{Q}_{\mu, approx}(x_0, s) = \frac{1}{\sqrt{1-s}} \exp \left[-\frac{1}{\pi} \int_0^\infty \ln[1 - s\hat{f}(k)] \frac{\sin(kx_0)}{k} dk \right]$$

- coincides with the exact \tilde{Q}_μ in the small x_0 expansion up to $O(x_0)$,
- coincides with the exact \tilde{Q}_μ in the small μ expansion up to $O(\mu)$.
- Captures the first order transition at short lifetimes,
- captures the second order transition at long lifetimes (x_m).

Non-trivial optimal exponent for finding **long-lived** targets

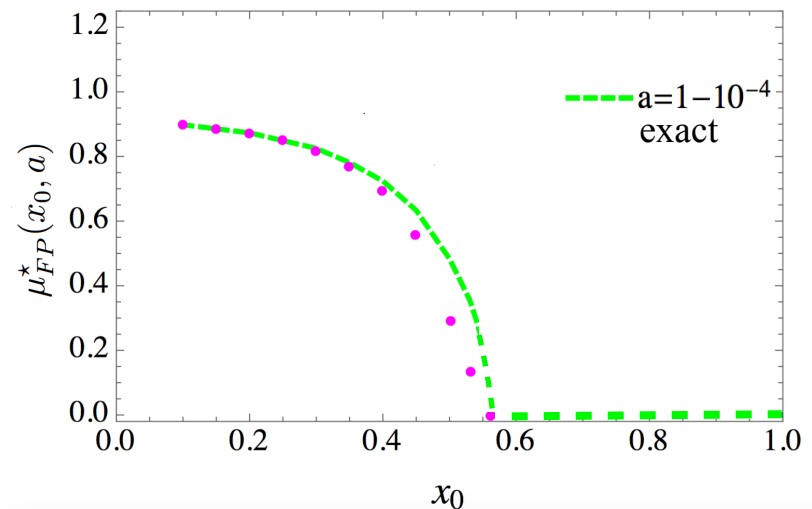
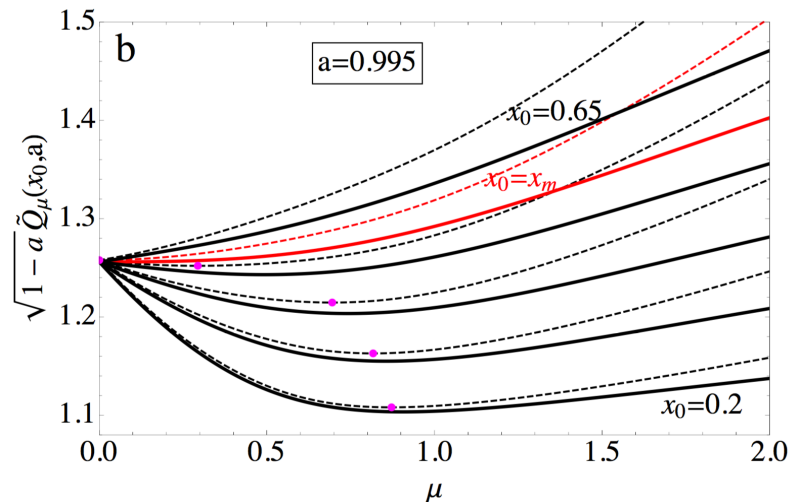
$a = 1$: mean first passage time (MFPT) is infinite $\forall f(\eta)$; all strategies are “bad”.

The divergence of the MFPT is due to few trajectories that take a very long time to cross the origin.

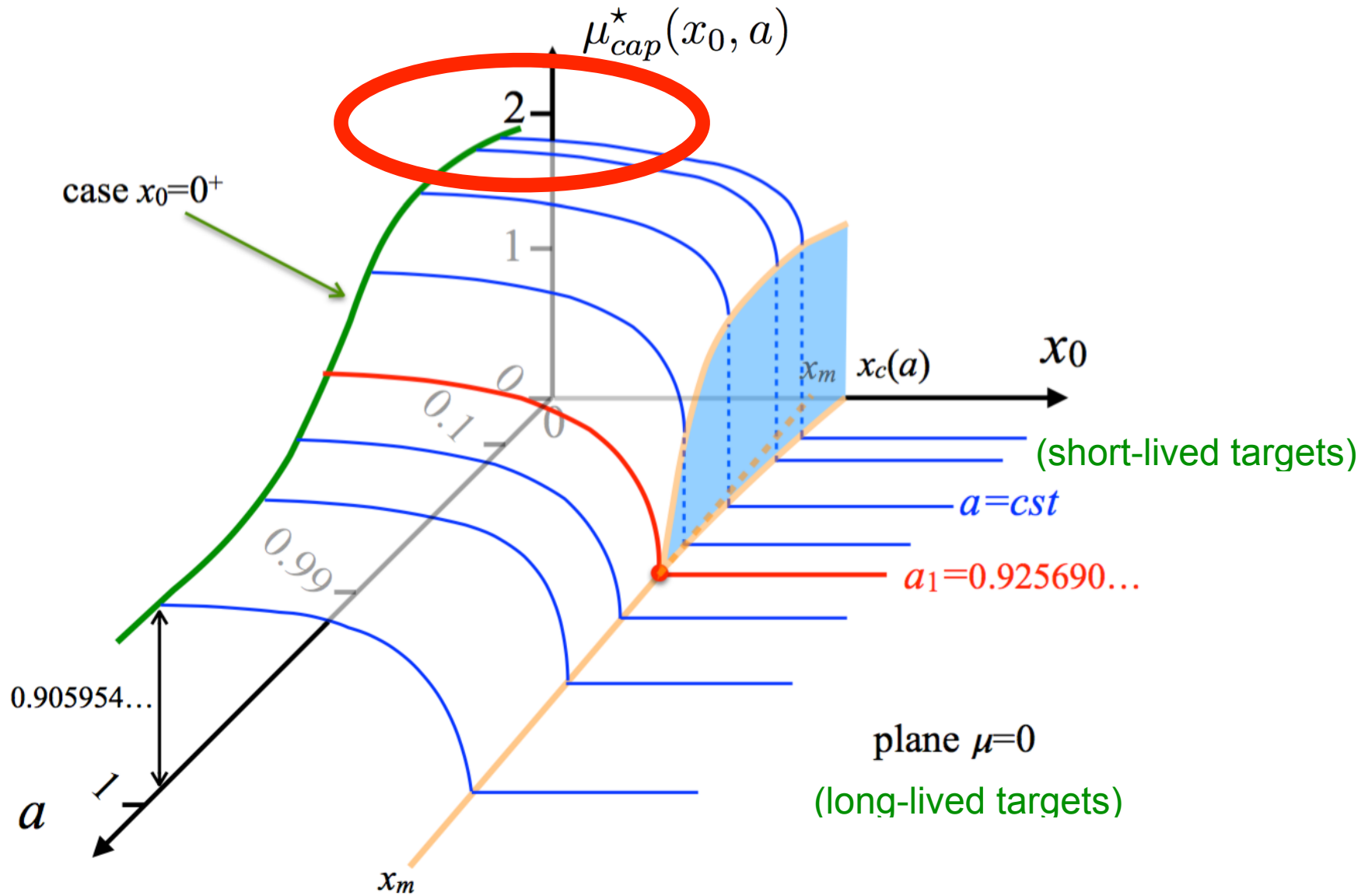
$a = 1 - \varepsilon$: capture probability is nearly one; the CMFPT is large but finite, and can be optimized.

$$T_\mu(x_0, a) \simeq \frac{1}{2} \tilde{Q}_\mu(x_0, a) \quad (\mu_{FP}^* \simeq \mu_{cap}^*)$$

$$\simeq \frac{1}{2\sqrt{1-a}} e^{-\frac{1}{\pi} \int_0^\infty \ln[1 - e^{-\left(\frac{u}{x_0}\right)^\mu}] \frac{\sin u}{u} du} \quad (\text{concav. approx})$$



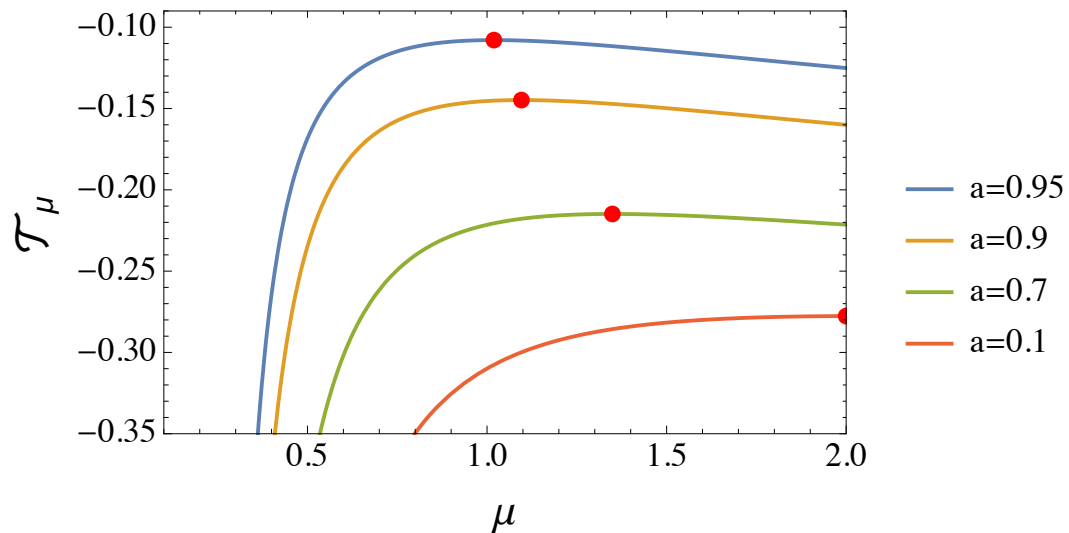
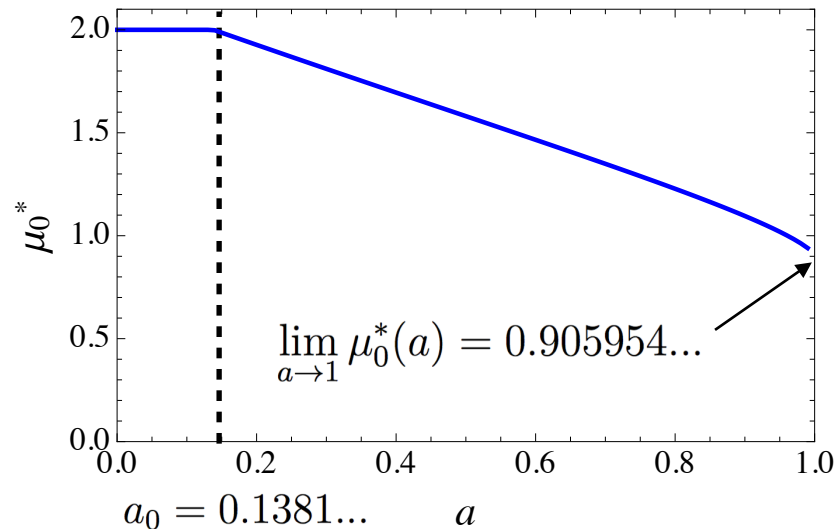
Other results



Starting very close to the target: $\lim_{x_0 \rightarrow 0^+} C_\mu(x_0, a) = \frac{1}{1 + \sqrt{1-a}}$ (universal)

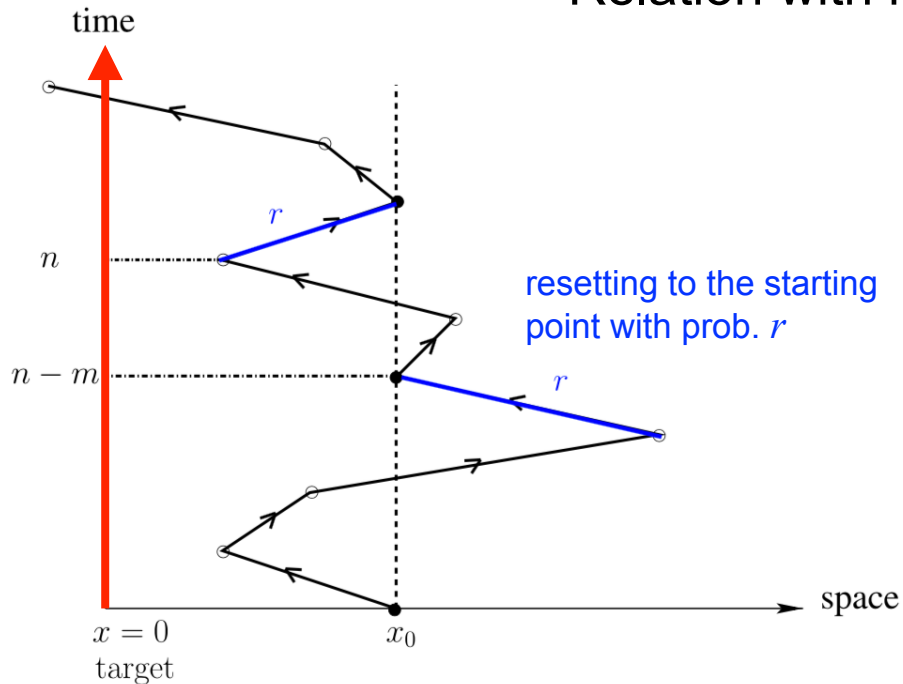
Starting close to the target: $C_\mu(x_0, a) \simeq \frac{1}{1 + \sqrt{1-a}} + x_0 \mathcal{T}_\mu(a) + \mathcal{O}(x_0^2)$

$$\mathcal{T}_\mu(a) = \frac{\sqrt{1-a}}{a\pi} \int_0^\infty \ln [1 - ae^{-|k|^\mu}] dk$$



“Advise”: If you start close to the target, move as Lévy if it is long-lived but move Gaussianly if it is short-lived.

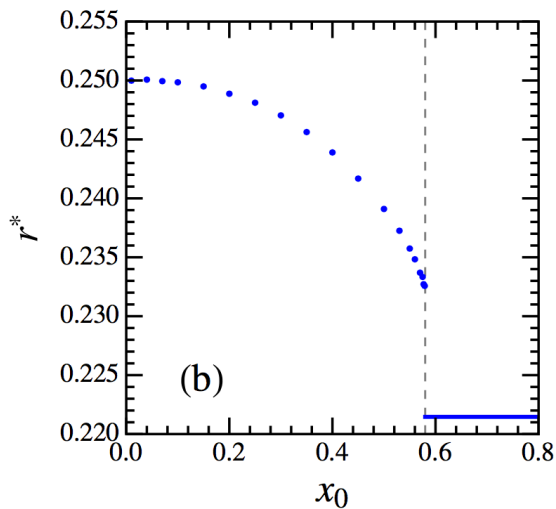
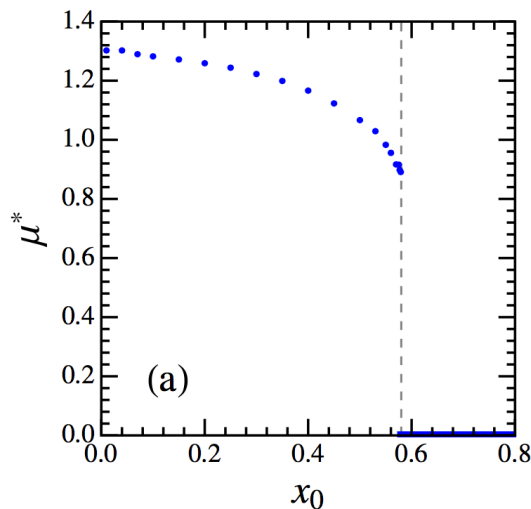
Relation with resetting processes



Mean first passage time:

$$T_{\mu}^{(resetting)}(x_0, r) = \frac{\tilde{Q}_{\mu}(x_0, 1 - r)}{1 - r\tilde{Q}_{\mu}(x_0, 1 - r)}$$

(Kusmierz, Majumdar, Sabhapandit & Schehr, PRL, 2014)



Optimization w.r. to two parameters! r and μ .

Conclusions

- Lévy flights can optimise the success of random searches with finite lifetime.
- The exponents are rather non-trivial for close-by targets and depend on the initial distance.
- Abrupt transitions for the optimal parameters, non-conventional tri-critical point.
- The infinite lifetime limit has a non trivial optimal search strategy.
- If exponential distribution of steps: “trivial” optimal distribution ($\langle \eta \rangle \rightarrow \infty$).
- Lévy searches can be advantageous in uncertain environments.
- Higher dimensions?
- Other target dynamics?
- Multiple searchers?

Thanks!